

Control Method for Multi-leg Voltage-Source Inverters

Ph. Delarue¹, A. Bouscayrol¹, E. Semail¹, B. François²,

¹ **L2EP Lille**, bât. P2, USTL, 59 655 Villeneuve d'Ascq cedex, France,

² **L2EP Lille**, Ecole Centrale de Lille, 59 655 Villeneuve d'Ascq cedex, France

Philippe.Delarue@univ-lille1.fr, Fax: 33-3-20-43-69-67,

URL: <http://www.univ-lille1.fr/l2ep/>

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Abstract

In this paper, a general and simple control method is proposed for any multi-leg voltage-source inverters. This strategy is based on a specific coding technique of the switching patterns. It is validated on an original 5-leg inverter, which supplies two independent induction machines. Applications to 3-leg and 4-leg structures are also presented. Finally a comparison with a standard Pulse Width Modulation points out its characteristics.

I. Introduction

In the last decades numerous works have been proposed to optimize the control of voltage-source inverters (VSI) [1, 2]: third harmonic injection, space vector strategy, flat-top modulation... Most of these inverters are 3-leg structures in order to supply AC machines. Indeed, these drives are growing in industrial applications thanks to dynamic machine controls [3].

But other specific inverter structures are now studied: 4-leg inverter for three-phase four-wire systems [4, 5], 5-leg inverter for a two-induction drive [6]... Moreover studies of multi-machine multi-converter systems are developed in order to propose original solutions [7]. For each of these non-classical structures, a specific control has been developed.

In this paper, a general and simple control method is proposed for any multi-leg voltage-source inverters. The aim is to have a general algorithm, which can be quickly implanted and easily modified if the inverter topology changes.

II. Modelling of a multi-leg VSI

II.1. Structure of the studied VSI

The studied converter links a DC voltage source V_{DC} to n AC current sources $i_1... i_n$. (Fig. 1). It is so composed of n legs of two power switches (one transistor and one diode in parallel), which are assumed to be turn-on and turn-off controlled.

As the leg n° n is arbitrarily chosen as potential reference, the converter leads to $n-1$ modulated phase-to-phase voltages $u_{1n}...u_{(n-1)n}$ between current-sources. In another hand, the inverter yields a modulated current i_{inv} to the DC voltage-source.

references of phase-to-phase voltages in order to impose different frequencies on both stator windings of the machines (i.e. to obtain two independent and balanced systems of three phase-to-neutral voltages [6]).

Conclusion

A general control method has been proposed in order to control any multi-leg voltage-source inverter. It has been validated for different structures: original 5-leg and 4-leg inverters, and a classical 3-leg one.

A specific coding allows a global strategy for any leg number. It can be easily implemented in a table. But, in another hand, it leads to a worse harmonic spectrum than a classical PWM control. Another method to define the non-used modulation patterns could be found in order to reduce these drawbacks.

But for a number of leg higher than 3, optimum PWM are more complex [4, 5, 11]. So this multi-leg control strategy is very interesting in practical cases in case of the number of leg may change (modular power structures [13]) or for inverters for a great number of legs. Supply of multi-phase machines, which are growing in industrial process, are concerned.

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